To Predict > To Design > To Perform

ME, ECE, BE Capstone Design Programs

Team 27: Mechanical Operation of the FMC Choke Throttle Valve **FMC Technologies** James Hamilton, Joseph Kowalski, Michael Leonpacher, Michael Roy, Henry Walton **Objective Statement**

Team 27 will design a valve attachment that will remotely actuate the functions of FMC Technologies' proprietary Flowline Choke Throttle valve. The design will streamline valve operations and always operate the valve in the correct sequence.

Engineering Specifications

- Only allow for operation of the valve in the correct order.
- Be able to output 150 foot-pounds of torque.
- Be environmentally sealed.
- Target weight of 50 pounds
- Last at least 1000 actuation cycles.
- Must turn ¼ turn for choke valve.
- Must make 5 revolutions and rise .95 inches for throttle valve.

Operational Principles

- Which function the actuator is turning is controlled by a detent system.
- The switching between the two functions of the torque-controlled rather actuator IS distance-controlled.
- The detent is used to ensure the proper operating order.



Sponsor: Mr. Alan Mohn, FMC Technologies

Motor

Actuator



FEA

- Completed for critical components (detenter, clutch teeth).
- Lowest Factor of Safety found was 6.21.
- Loads based on fixed geometries and 150 ft-lbs torque input.
- ANSYS (shown at left) was used to determine deflections and stresses on a micro-scale.



College of Engineering Department of Mechanical & Industrial Engineering



Choke Throttle Valve

Drive Can with Detent Mechanism

Budget	
Total Available Budget	\$1,500.00
Raw Materials	\$431.86
Stock Parts	\$436.20
Hydraulic Motor	\$267.68
Shipping	\$158.83
Total Supply Cost	\$1,294.57
Remaining Budget	\$205.43

Manufacturing

- technicians.
- required for sliding parts.

Testing Results

- unpressurized valve.
- actuation.

Safety

maximum of 150 foot-pounds.

Budget

motor.





Parts manufactured out of low carbon steel. Machining methods used were CNC lathe or CNC mills as recommended by LSU machine shop

Tolerances of 1 to 2 thousandths of an inch were Standard tolerances of 5 thousandths of an inch were used unless otherwise specified.

The actuator was successfully able to transmit 150 foot-pounds of torque and open and close an

The actuator operated in the correct order. The final design left an input for remote

The actuator incorporated a torque limiter to prevent the transmission of any torque over the

• Were the prototype designed for mass production, the per unit cost would actually be around \$1300, inclusive of a

Advisors: Dr. Ram Devireddy, Capt. Dave Giurintano